



# Connect Tech Inc.

## **Xtreme MIO J1708 API Manual** *API Software Reference*

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# 1 Revision History

Revision	Date	Author(s)	Change
0.00	October 23, 2012	HJ	Added content for J1708 API

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## 3 Contents and Audience

This manual describes an API (Application Programming Interface) for interface to a DLL which facilitates operations with the PCI card designed according to the requirements of XTREME MIO. Its content is intended for a technical audience, and is oriented toward providing information for software and/or hardware engineering people.

## 4 Introduction

Throughout this document there are references to the **XTREME MIO Technical Users Manual**, which describes the operation of the J1708 port.

This DLL is a collection of function calls that ease the application software development effort.

The application will need to include library **prf636.lib** which is in the DLL directory of the package. Header file **prf636dll.h** has all the API declarations which are described in the API Declarations section, below.

It is recommended to first read the hardware manual Section 6 to understand J1708 operation.

## 5 API Declarations

### OpenJ1708

---

Opens a J1708 port returning a handle for use with other J1708 functions.

```
HANDLE _stdcall OpenJ1708(int index );
```

#### Parameters

index    index to device number (1 = first port)

#### Returns Values

INVALID\_HANDLE\_VALUE on failure otherwise device handle on success.

#### Remarks

Non-blocking.

### CloseJ1708

---

Closes a J1708 port previously opened using OpenJ1708 and frees resources.

```
BOOL _stdcall CloseJ1708(HANDLE handle);
```

#### Parameters

handle    handle to device returned on OpenJ1708.

#### Returns Values

nonzero on success.

#### Remarks

Non-blocking.

### SetupJ1708

---



Configures a J1708 port parameters.

```
int _stdcall SetupJ1708(  
    HANDLE devHandle,  
    J1708_CONFIG *j1708Config  
);
```

#### Parameters

devHandle	handle to device returned on OpenJ1708
j1708Config	pointer to configuration structure

#### Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

#### Remarks

Non-blocking. Following is the J1708\_CONFIG structure (see hardware manual section 7.2)

```
typedef struct _J1708_CONFIG {  
    ULONG mask_good_tx;        // Control Register bit 0  
    ULONG Tx_Priority;         // TX Priority register, valid ranges 0-7  
    ULONG Tx_Problem_Limit;    // TX Problem Limit register, valid ranges 2-254  
    ULONG Rx_EOM_Level;        // RX EOM Level register, valid ranges 0-15  
    ULONG Rx_Afull_Level;      // RX Afull Level register, valid ranges 1-31  
}J1708_CONFIG;
```

### ReadJ1708

Reads from a J1708 port.

```
int _stdcall ReadJ1708(  
    HANDLE devHandle,  
    char *buffer,  
    int bufferSize,  
    int *numRead  
);
```

#### Parameters

devHandle	handle to device returned on OpenJ1708
buffer	pointer to buffer to read to
bufferSize	size of buffer in bytes
numRead	on return contains the actual number of bytes read

#### Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

#### Remarks

Blocking.

The application should pass a buffer of sufficient size to this API call, so that there is enough space for the read data, otherwise it will return **J1708\_STATUS\_INSUFFICIENT\_BUFFER** and the application will get the number of data bytes available by the **GetReadDataAvailJ1708** API call.

### WriteJ1708

Writes to a J1708 port.

```
int _stdcall WriteJ1708(  
    HANDLE devHandle,  
    char *buffer,
```



```
int bufferSize  
);
```

Parameters

devHandle	handle to device returned on OpenJ1708
buffer	pointer to buffer to write
bufferSize	number of bytes in buffer to write

Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

Remarks

Blocking.

---

**GetReadDataAvailJ1708**

Get number of bytes available to read on a J1708 port.

```
int _stdcall GetReadDataAvailJ1708(  
    HANDLE devHandle,  
    int *dataAvail  
);
```

Parameters

devHandle	handle to device returned on OpenJ1708
dataAvail	on return contains number of bytes ready to read

Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

Remarks

Non-blocking.

---

**GetReadStatusJ1708**

Get read status of a J1708 port.

```
int _stdcall GetReadStatusJ1708(  
    HANDLE devHandle,  
    char *buffer,  
    int bufferSize  
);
```

Parameters

devHandle	handle to device returned on OpenJ1708
buffer	pointer to buffer to receive status information status values include BUF_OVERRUN
bufferSize	size in bytes of buffer (must be at least 4)

Note in future this function may be extended to return more information if necessary, so this is why the buffer is not a pointer to just a ULONG.

Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses

Remarks

Non-blocking

---

**GetWriteStatusJ1708**

Get write status of a J1708 port.

```
int _stdcall GetWriteStatusJ1708(  
    HANDLE devHandle,  
    char *buffer,  
    int bufferSize  
);
```

**Parameters**

devHandle	handle to device returned on OpenJ1708
buffer	pointer to buffer to receive status information status values include STATUS_J1708_TX_ABORTED and STATUS_J1708_TX_PROB
bufferSize	size in bytes of buffer (must be at least 4)

Note in future this function may be extended to return more information if necessary, so this is why the buffer is not a pointer to just a ULONG

**Returns Values**

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

**Remarks**

Non-blocking.

---

**AbortJ1708TX**

Abort a transmit in progress on a port.

```
int _stdcall AbortJ1708TX(HANDLE devHandle);
```

**Parameters**

devHandle	handle to device returned on OpenJ1708
-----------	--

**Returns Values**

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

**Remarks**

Non-blocking.

---

**Write\_USER\_TA\_J1708**

Set USER\_TA values on a J1708 port.

```
int _stdcall Write_USER_TA_J1708(  
    HANDLE devHandle,  
    USER_TA_DLL *userTA  
);
```

**Parameters**

devHandle	handle to device returned on OpenJ1708
userTA	pointer to USER_TA values to set



#### Returns Values

J1708\_STATUS\_OK on success, otherwise statuses defined in api return statuses.

#### Remarks

Non-blocking. Following is the USER\_TA\_DLL structure (see hardware manual section 7.2.9)

```
typedef struct _USER_TA_DLL {  
    UCHAR Value;           // User-Ta value, valid ranges (0-31)  
    UCHAR In_Effect;       // User Ta in effect, valid ranges (0-1)  
    UCHAR Ignore           // Ignore Ta in effect valid ranges (0-1)  
}USER_TA_DLL;
```

## 6 API Return Values

The following definition is from driver to application via DLL.

```
//  
// receive buffer overrun in the driver  
//  
#define BUF_OVERRUN                0xb0000001  
  
// GetWriteStatusJ1708 values. For more detail refer to hardware manual section 7.1.2.1  
//  
// this indicates that there is a TX abort error on J1708  
//  
#define STATUS_J1708_TX_ABORTED    0xb0000040  
//  
// this indicates that there is a TX problem error on J1708  
//  
#define STATUS_J1708_TX_PROB       0xb0000080
```

The following definition is from dll to application

```
#define J1708_STATUS_OK                0x0000  
#define J1708_STATUS_INVALIDPARAM     0x0001  
#define J1708_STATUS_IOFAILURE        0x0002  
#define J1708_STATUS_NOT_INIT         0x0003  
#define J1708_STATUS_INSUFFICIENT_BUFFER 0x0004
```

## 7 J1708 DLL API Operation

### 7.1 Opening J1708 Port

The application will use **OpenJ1708** to open J1708 Port, according to the following sample code.

```
HANDLE hDriver = OpenJ1708( unit );
```

Where unit is board index starting from 1, enumerated as J1708\_PORT1, J1708\_PORT2.

### 7.2 Set Up J1708 Port

Please read hardware manual section 7.1 to understand the operation of J1708. The application will need to setup J1708 port using API **SetupJ1708**, no read or write operation is permitted until setup is done. This API takes **J1708\_CONFIG** structure as an argument. The following code will setup the port.

```
J1708_CONFIG j1708Config = {0};  
// see section 7.2 of hardware manual for details of parameters  
j1708Config.mask_good_tx      = 0;  
j1708Config.Tx_Priority      = 7;  
j1708Config.Tx_Problem_Limit = 111;  
j1708Config.Rx_Afull_Level   = 11;  
j1708Config.Rx_EOM_Level     = 11;  
SetupJ1708( hDriver, &j1708Config);
```

Then the application can read and write to the J1708 port.

### 7.3 Read from J1708 Port

The application will use **ReadJ1708** API to read data from J1708 port. The following code shows usage of this API call.

```
charbuffer[MAX_BUF_SIZE];  
ULONG      ret, bufReq;  
int         numRead, i;  
ULONG      readStatus;
```

```
ReadTryAgain:  
ret = ReadJ1708(hDriver, buffer, bufReq, &numRead);
```

If the returned status is 'J1708\_STATUS\_OK' then the application should check the status of the read. The following code shows it

```
ret = GetReadStatusJ1708( hDriver, (char *)&readStatus, sizeof readStatus );  
if( ret == J1708_STATUS_OK )  
{  
    if( readStatus & BUF_OVERRUN == BUF_OVERRUN )  
    {  
        printf("J1708 BUF_OVERRUN error\n");  
        goto ReadTryAgain;  
    }  
}
```

If read operation succeeds, then it will get one J1708 complete packet.

The application should pass a buffer of sufficient size to this API call, so that there is enough space for the read data, otherwise it will return **J1708\_STATUS\_INSUFFICIENT\_BUFFER** and the application will get the number of data bytes available by the **GetReadDataAvailJ1708** API call.

If the driver buffer has overrun then the application should find out how much data is available and read all data. The data received is good even though overrun has happened.

```
if (ret == J1708_STATUS_INSUFFICIENT_BUFFER || readStatus & BUF_OVERRUN)
{
    int lastStatus = ret;
    bufReq = 0;
    // buffer was not big enough so find out how much space is needed and try again
    ret = GetReadDataAvailJ1708(pContext->hDriver, &bufReq);
    if( ret == J1708_STATUS_OK )
    {
        // ensure we have enough buffer available to retry with larger size
        if( bufReq > MAX_BUF_SIZE )
        {
            printf("J1708 GetReadDataAvailJ1708 error, buffer required bigger than maximum size\n");
            bufReq = MAX_BUF_SIZE;
        }

        if(lastStatus == J1708_STATUS_INSUFFICIENT_BUFFER)
        {
            goto ReadTryAgain;
        }
    }
    else
        printf("J1708 GetReadDataAvailJ1708 error %d\n", ret);
}
```

## 7.4 Write to J1708 Port

The application will use **WriteJ1708** API call to write data to J1708 port. The following code shows usage of the API call.

```
charBUF[MAX_BUF_SIZE];
charbuffer;
ULONG      ret;
int        i, bufSize;
ULONG      writeStatus;

ret = WriteJ1708(hDriver, buffer, bufSize);
```

If the returned status is 'J1708\_STATUS\_OK' then the application should check the status of the write. If the write operation status is 'STATUS\_J1708\_TX\_PROB' then the application should abort the current transmission and retransmit the last packet. The following code shows it

```
ret = GetWriteStatusJ1708( hDriver, (char *)&writeStatus, sizeof writeStatus );
if( ret == J1708_STATUS_OK )
{
    if ((writeStatus & STATUS_J1708_TX_ABORTED) == STATUS_J1708_TX_ABORTED)
    {
        printf("J1708 current packet transmission aborted\n");
    }
    if((writeStatus & STATUS_J1708_TX_PROB) == STATUS_J1708_TX_PROB)
    {
        printf("J1708 Tx problem limit, abort current packet transmission\n");
        abort the current packet transmission
        if( !AbortJ1708TX( hDriver ) )
        {
            printf("J1708 AbortJ1708TX failed");
        }
    }
}
else
    printf("J1708 GetStatusJ1708 failed error code = %d\n", ret);
```

## 8 Device Listing

After driver is installed the list of devices is available for viewing in device manager (Control Panel -> System -> Device Manager). The following picture shows the listing of J1708 port installed, marked in blue.

